## Thursday March 21

## Topics for this Lecture:

- Rotational
- Angular momentum
*Actual class-content for lecture likely to be somewhat different from this. Guest lecture given by Dr. Piccard.
- Assignment 9 due Friday
- Pre-class due 15min before class
- Help Room: Here, 6-9pm Wed/Thurs
- SI: Morton 226, M\&Tu 6:10-7:20pm
- Office Hours: This week by appointment (meisel@ohio.edu)
- Midterm 2: Monday April 1st

$$
\text { 7:15-9:15pm Morton Hall Room } 201
$$

## - Fun facts to know \& tell:

| Equations for kinematics in $1 D$ \& Newton's Laws apply to rotational motion as well, by subsituting the appropriate quantities: |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Linear Quantity |  |  | Corresponding Rotational Quantity |  |  |
| Quantity | Variable | SI units | Quantity | Variable | SI units |
| length | X | m | angle | $\theta=\mathrm{s} / \mathrm{r}$ | rad |
| velocity | $\mathrm{v}=\Delta \mathrm{x} / \Delta \mathrm{t}$ | $\mathrm{m} / \mathrm{s}$ | angular velocity | $\omega=\Delta \theta / \Delta t$ | $\mathrm{rad} / \mathrm{s}$ |
| acceleration | $\mathrm{a}=\Delta \mathrm{v} / \Delta \mathrm{t}$ | $\mathrm{m} / \mathrm{s}^{2}$ | angular acceleration | $\alpha=\Delta \omega / \Delta \mathrm{t}$ | $\mathrm{rad} / \mathrm{s}^{2}$ |
| mass | m | kg | moment of inertia | I (formula depends on object shape) | $\mathrm{kg}^{*} \mathrm{~m}^{2}$ |
| force | $\mathrm{F}=\mathrm{ma}$ | N | torque | $\tau=\mathrm{I} \alpha$ | $\mathrm{N}^{*} \mathrm{~m}$ |
| momentum | $p=m v$ | kg*m/s | angular momentum | $\mathrm{L}=\mathrm{I} \omega$ | $\mathrm{kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$ |

Consider two masses on a rod rotating as shown. In case A, the masses are at the end of the rod. In case B the same 2 masses are closer to the center.
If the same torque is applied to each situation, which arrangement of masses has the lowest angular acceleration?

B. B
C. Both have the same


1. $\tau=I \alpha=F^{\star} r^{*} \sin (\theta)=$ same for all
2. $\alpha=\tau / I$
3. The mass for case $A$ is less concentrated toward the axis of rotation. So, case A has a larger moment of inertia, I.
4. From (2), larger I means smaller $\alpha$. ... So case A will have the lowest $\alpha$.

Consider two masses on a rod that is attached to an axle, rotating as shown. The masses are placed identically in each situation. In each case the rod (massless) is turned by pulling a string wrapped around the center axle (also massless). The center axle in case $B$ has a much larger radius. If the force is the same, which situation has the smallest angular acceleration?

## A. A

B. B
C. Both have the same


1. $\tau=I \alpha=F^{\star} r^{*} \sin (\theta)$
2. $\alpha=\tau / I$
3. The masses are distributed identically, so both have the same moment of inertia, I.
4. However, the force $F$ in case $A$ is applied at a shorter distance $r$ from the axis of rotation. So, the applied torque is smaller in case $A$.
5. From (2), smaller $\tau$ means smaller $\alpha$....So case A will have the lowest $\alpha$.

A T-shaped rotating post, with a mass M and radius r , has two point-like masses of mass $M$ positioned a distance $R$ from the rotation axis, at the end of the $T$, as pictured. A string that is wrapped around the base of the post runs through a pulley and is attached to a hanging mass $\mathrm{m} . \mathrm{M}=1.0 \mathrm{~kg}, \mathrm{R}=0.5 \mathrm{~m}, \mathrm{~m}=0.1 \mathrm{~kg}$, and $\mathrm{r}=0.1 \mathrm{~m}$. What is the total moment of inertia of the post (cylinder) and its masses?
(A) $5 \times 10^{-3} \mathrm{~kg}^{*} \mathrm{~m}^{2}$
(B) $5 \times 10^{-2} \mathrm{~kg}^{*} \mathrm{~m}^{2}$
(C) $5 \times 10^{-1} \mathrm{~kg}^{\star} \mathrm{m}^{2}$
(D) $5.0 \mathrm{~kg}^{*} \mathrm{~m}^{2}$

1. The moment of inertia for a mutli-component object is just the sum of the moment of inertia for the components: $\mathrm{I}_{\text {total }}=\Sigma \mathrm{I}_{\mathrm{i}}$
2. The multi-component object here is a cylinder plus two point masses.
3. $\mathrm{I}=\mathrm{I}_{\mathrm{cyl}}+\mathrm{I}_{\text {point }, 1}+\mathrm{I}_{\text {point }, 2}$
4. $I=(1 / 2) M r^{2}+M R^{2}+M R^{2}$
5. $\mathrm{I}=(1 / 2)(1.0 \mathrm{~kg})(0.1 \mathrm{~m})^{2}+2^{\star}(1.0 \mathrm{~kg})(0.5 \mathrm{~m})^{2}$
6. $\mathrm{I}=0.005 \mathrm{~kg}^{\star} \mathrm{m}^{2}+0.5 \mathrm{~kg}^{\star} \mathrm{m}^{2} \approx 0.5 \mathrm{~kg}^{*} \mathrm{~m}^{2}$


$$
\begin{aligned}
& \mathrm{I}_{\text {point }}=\mathrm{MR}^{2} \\
& \mathrm{I}_{\text {cylinder }}=(1 / 2) \mathrm{Mr}^{2}
\end{aligned}
$$

## Angular Momentum, L

- Recall: Equations for kinematics in 1D \& Newton's Laws apply to rotational motion as well, by subsituting the appropriate quantities:

| Linear Quantity |  |  | Corresponding Rotational Quantity |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Quantity | Variable | SI units | Quantity | Variable | SI units |
| length | x | m | angle | $\theta=\mathrm{s} / \mathrm{r}$ | rad |
| velocity | $\mathrm{v}=\Delta \mathrm{x} / \Delta \mathrm{t}$ | $\mathrm{m} / \mathrm{s}$ | angular velocity | $\omega=\Delta \theta / \Delta \mathrm{t}$ | $\mathrm{rad} / \mathrm{s}$ |
| acceleration | $\mathrm{a}=\Delta \mathrm{v} / \Delta \mathrm{t}$ | $\mathrm{m} / \mathrm{s}^{2}$ | angular acceleration | $\alpha=\Delta \omega / \Delta \mathrm{t}$ | $\mathrm{rad} / \mathrm{s}^{2}$ |
|  | m | kg | moment of inertia | I (formula depends on <br> object shape) | $\mathrm{kg}^{*} \mathrm{~m}^{2}$ |
| mass | m | ma | N | torque | $\mathrm{N}^{*} \mathrm{~m}^{2}=\mathrm{I} \alpha$ |
| force | $\mathrm{F}=\mathrm{m}$ | $\mathrm{kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$ |  |  |  |
| momentum | $\mathrm{p}=\mathrm{mv}$ | $\mathrm{kg} \mathrm{kg}^{*} \mathrm{~s}$ | angular momentum | $\mathrm{L}=\mathrm{I} \omega$ |  |

- Just as linear momentum (p) is conserved in the absence of an external force, angular momentum (L) is conserved in the absence of an external torque.
- $\mathrm{L}_{\text {initial }}=\mathrm{L}_{\text {final }}$
- $\mathrm{I}_{\text {initial }}{ }^{\star} \omega_{\text {initial }}=\mathrm{I}_{\text {final }}{ }^{\star} \omega_{\text {final }}$
- Angular momentum, $L$, is a vector whose direction corresponds to the spin-axis.



## Angular Momentum Conservation

- Consequence 1:

A spinning object keeps pointing in the same direction
-Spinning objects require an external torque to change their direction
-So, a spinning object will tend to stay pointed the way it is originally pointed


## Angular Momentum Conservation

- Consequence 2:

An object whose mass distribution changes will change rotation rate \& vice versa
-E.g. Figure skater:

-E.g. Pulsar (ultra-dense,ultra-fast spinning remnant from a supernova)

~mass of sun compressed to ~size of city, spinning at ~60-60,000 RPM,
Left over from a massive stellar explosion.

A professor sits on a turntable holding two 2-kg masses in their hands. Their arms are folded close to their body. They are rotating.
When the professor stretches their arms out (with the masses in-hand), the angular velocity of the professor will:

## A. Increase

## B. Decrease

C. Stay the Same


1. Angular momentum is conserved.
2. So, $L=I^{*} \omega$ = constant.
3. When the masses are moved outward, the mass distribution is less concentrated, and so the moment of inertia, I, increases.
4. To maintain $L, \omega$ must decrease.

Each Red dot represents a 1kg mass attached to a massless turntable. The inner circle has a radius half that of the outer circle. If the masses start in Configuration A and move to Configuration B while the turntable is spinning, how does the final moment of inertia of the turntable compare to the initial? (assume no external torque)


## A. Greater

B. Smaller
C. Same

1. The masses are moved inward, the mass distribution is more concentrated, and so the moment of inertia, I, decreases.

Each Red dot represents a 1kg mass attached to a massless turntable. The inner circle has a radius half that of the outer circle. If the masses start in Configuration A and move to Configuration B while the turntable is spinning, how does the final angular momentum of the turntable compare to the initial? (assume no external torque)

> A. Greater
> B. Smaller
> C. Same

1. Angular momentum is conserved in the absence of external torques.
2. There are no external torques, so $\mathrm{L}_{\text {initial }}=\mathrm{L}_{\text {final }}$

Each Red dot represents a 1kg mass attached to a massless turntable. The inner circle has a radius half that of the outer circle. If the masses start in Configuration $A$ and move to Configuration $B$ while the turntable is spinning, how does the final angular velocity of the turntable compare to the initial? (assume no external torque)

(B)


1. Angular momentum is conserved.
2. So, $L=I^{\star} \omega$ = constant.
3. When the masses are moved inward, the mass distribution is more concentrated, and so the moment of inertia, I, decreases.
4. To maintain $L, \omega$ must increase.

Suppose a rod of negligible mass has a 2.0kg object on each end. The rod is 1.0 m long and is spinning at an angular speed of $5.0 \mathrm{rad} / \mathrm{s}$. What is the angular momentum?
(A) $2 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(B) $4 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(C) $5 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(D) $10 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$


1. $\mathrm{L}_{\mathrm{i}}=\mathrm{I}_{\mathrm{i}} \mathrm{\omega}_{\mathrm{i}}$
2. $L_{i}=\left(M R_{i}^{2}+M R_{i}^{2}\right) \omega_{i}$
3. $\mathrm{L}_{\mathrm{i}}=2(2.0 \mathrm{~kg})(0.50 \mathrm{~m})^{2}(5.0 \mathrm{rad} / \mathrm{s})=5 \mathrm{~kg} \mathrm{~m}^{2} / \mathrm{s}$

Suppose a rod of negligible mass has a 2.0kg object on each end. The rod is 1.0 m long and is spinning at an angular speed of 5.0rad/s. Little motors move the masses inward by 0.25 m .
What is the new angular momentum?
(A) $2 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(B) $4 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(C) $5 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$
(D) $10 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$


1. There are no external torques, so angular momentum is conserved.
2. $\mathrm{L}_{\mathrm{f}}=\mathrm{L}_{\mathrm{i}}=5 \mathrm{~kg}^{*} \mathrm{~m}^{2} / \mathrm{s}$

Suppose a rod of negligible mass has a 2.0kg object on each end. The rod is 1.0 m long and is spinning at an angular speed of $5.0 \mathrm{rad} / \mathrm{s}$. Little motors move the masses inward by 0.25 m . What is the new angular speed?
(A) $2.5 \mathrm{rad} / \mathrm{s}$
(B) $5 \mathrm{rad} / \mathrm{s}$
(C) $10 \mathrm{rad} / \mathrm{s}$
(D) $20 \mathrm{rad} / \mathrm{s}$


1. $\mathrm{L}_{\mathrm{i}}=5 \mathrm{~kg} \mathrm{~m}^{2} / \mathrm{s}=\mathrm{I}_{\mathrm{i}} \omega_{\mathrm{i}}=\mathrm{L}_{\mathrm{f}}=\mathrm{I}_{\mathrm{f}} \omega_{\mathrm{f}}$
2. $\omega_{f}=L_{i} / I_{f}$
3. $\mathrm{I}_{\mathrm{f}}=2^{*}\left(\mathrm{Mr}^{2}\right)=2^{*}(2 \mathrm{~kg})(0.25 \mathrm{~m})^{2}=0.25 \mathrm{~kg}^{*} \mathrm{~m}^{2}$
4. $\omega_{\mathrm{f}}=\mathrm{L}_{\mathrm{i}} / \mathrm{If}_{\mathrm{f}}=\left(5 \mathrm{~kg}^{\star} \mathrm{m}^{2} / \mathrm{s}\right) /\left(0.25 \mathrm{~kg}^{\star} \mathrm{m}^{2}\right)=20 \mathrm{rad} / \mathrm{s}$

Each Red dot represents a 1kg mass on a massless turntable.
The blue dot is 2 kg .
The inner circle has a radius half that of the outer circle.
If the masses start in Configuration A and move to Configuration B while the turntable is spinning, how does the final angular speed of the turntable compare to the initial? (assume no external torque)

## A. Greater <br> B. Smaller <br> C. Same

1. $L_{i}=I_{i} \omega_{i}=L_{f}=I_{f} \omega_{f}$
2. $I_{i}=2 *\left(M_{\text {red }}\right)\left(R_{\text {red }, i}\right)^{2}+\left(M_{\text {blue }}\right)\left(R_{\text {blue }, i}\right)^{2}$
3. $R_{\text {blue }, i}=(1 / 2)^{\star} R_{\text {red }, i}$ and $M_{\text {blue }}=2 * M_{\text {red }}$, so ... $I_{i}=(5 / 2)^{\star}\left(M_{\text {red }}\right)\left(R_{\text {red }, i}\right)^{2}$.
4. $I_{f}=2 *\left(M_{\text {red }}\right)\left(R_{\text {red }, f}\right)^{2}+\left(M_{\text {blue }}\right)\left(R_{\text {blue }, f}\right)^{2}$
5. Since $R_{\text {red }, f}=(1 / 2)^{\star} R_{\text {blue }, f}$ and $M_{\text {blue }}=2 * M_{\text {red }} \ldots \quad I_{f}=(5 / 2)^{\star}\left(M_{\text {red }}\right)\left(R_{\text {blue }, f}\right)^{2}$
6. Since $R_{\text {blue }, f}=R_{\text {red, } i} \ldots I_{i}=I_{f}$
7. Since $L=$ constant and $I=$ constant, $\omega=$ constant.

$$
I_{\text {point }}=\mathrm{MR}^{2}
$$

## Conservation of Angular Momentum for Elliptical Orbits

- Angular momentum is conserved in any system without an external torque.
-This includes objects in elliptical orbits, like planets in the solar system.
- In an elliptical orbit, the orbiting objects moves further from \& closer to the more massive object it is orbiting as it orbits.
-The furthest distance is called apogee; the closest
 distance is called perigee.
- Since angular momentum is conserved, $\mathrm{L}_{\text {apogee }}=\mathrm{L}_{\text {perigee }}$.
- In both cases, $L=I \omega$, and $I=M_{\text {satellite }} R^{2}$, but $R_{\text {apogee }}>R_{\text {perigee }}$.
-This means $\omega_{\text {perigee }}>\omega_{\text {apogee }}$ (since $L$ is the same).
- Consequently, the satellite moves faster as it approaches the object it slows down as it moves away.
- This means, "planets sweep out equal areas in equal times",


Haley's comet completes a full orbit of the sun every $\sim 75$ years.
At closest approach to the sun (perihelion), it is moving at $54 \mathrm{~m} / \mathrm{s} 0.57 \mathrm{AU}$ from the sun. How fast is Haley's comet moving when it is farthest from the sun (aphelion) at 35AU?
(A) $0.02 \mathrm{~m} / \mathrm{s}$
(B) $0.88 \mathrm{~m} / \mathrm{s}$
(C) $27 \mathrm{~m} / \mathrm{s}$
(D) $54 \mathrm{~m} / \mathrm{s}$


1. $\mathrm{L}_{\text {perihelion }}=\mathrm{I}_{\text {perhelion }} \omega_{\text {perhelion }}=\mathrm{L}_{\text {aphelion }}=\mathrm{I}_{\text {aphelion }} \omega_{\text {aphelion }}$
2. $L_{\text {perihelion }}=\left(M_{\text {Haley }} R_{\text {perihelion }}^{2}\right)\left({ }^{v_{\text {perihelion }}} / R_{\text {perihelion }}\right)=M_{H} r_{p} v_{p}$
3. $L_{\text {aphelion }}=M_{H} r_{a} v_{a}$
4. $M_{H} r_{a} v_{a}=M_{H} r_{p} v_{p} \ldots$ so: $r_{a} v_{a}=r_{p} v_{p}$
5. $v_{a}=\frac{r_{p} v_{p}}{r_{a}}=\frac{(0.57 A U)\left(54^{m} / \mathrm{s}\right)}{35 A U}=0.88 \mathrm{~m} / \mathrm{s}$

$$
\begin{aligned}
& I_{\text {point }}=M R^{2} \\
& v=r \omega
\end{aligned}
$$

1AU = 1 "astronomical unit" = 1 Earth-Sun distance

